

Tutorial 01: First Steps Using the VLFL-Toolbox for Solid Object Design

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Complete List of all Tutorials with Publishable MATLAB Files of this Solid-Geometries Toolbox

The following topics are covered and explained in the specific tutorials:

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- Tutorial 16: Create Tube-Style Solids by Succeeding Polygons
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- Tutorial 18: Analyzing and modifying STL files from CSG modeler (Catia)
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- Tutorial 24: Automatic Creation of a Joint Limitations
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- Tutorial 26: Create Mechanisms using Universal Planar Links
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- Tutorial 35: Creation of Kinematic Chains and Robot Structures
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- Tutorial 42: Performing FEM Stress and Displacement Analysis and Structural Optimization of Solids
- Tutorial 43: Performing FEM Structural Optimization (CAO) and Topological Optimization (SKO) of Solids
- Tutorial 44: Creation of solids and kinematics from 3D curves and transformation matrices
- Tutorial 45: Creation of Solids using the SG-Coder - SGofCPLcommand
- Tutorial 46: Creating Fischertechnik compatible gear boxes using SGofCPLcommand
- Tutorial 47: Creating four-joints by 3 pose synthesis

Motivation for this tutorial: (Originally SolidGeometry 1.1 required)

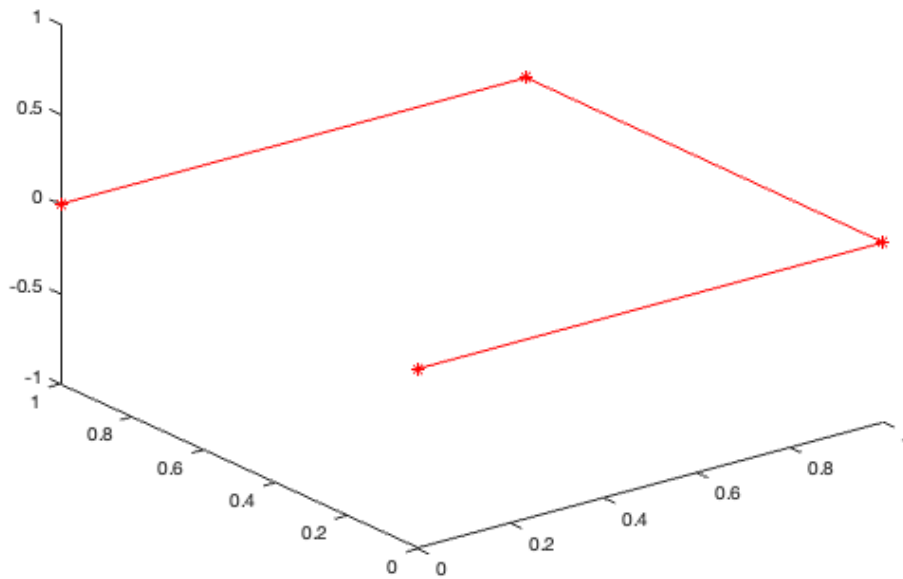
1. Creating and visualizing a simple base-contour by four 2D-points

A point list is a $n \times 2$ array. The number n is the number of 2D coordinate points $[x \ y]$. In general, such a point list can be the basis for designing a boundary surface model. We start with some simple functions to display polygons:

- **PLplot** to plot in 3D a $n \times 2$ point list (PL).

```
PL=[ 0 0; 1 0; 1 1; 0 1]
PLplot(PL);
```

```
PL =
     0     0
     1     0
     1     1
     0     1
```



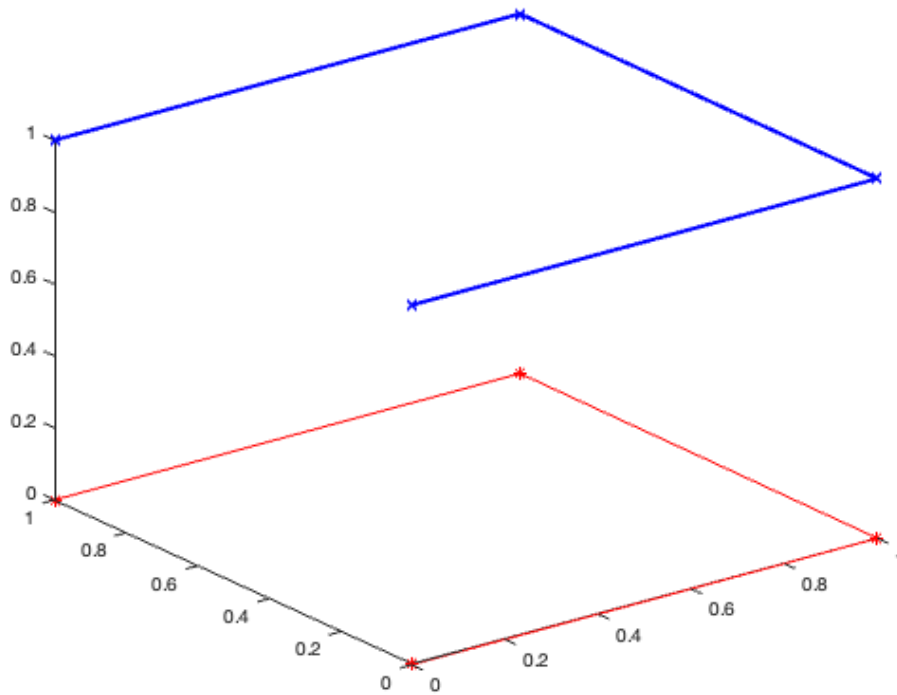
2. Append a 3rd coordinate column to get a vertex list

A vertex list is a $n \times 3$ array. The number n is the number of 3D coordinate points $[x \ y \ z]$. In fact, the point list can be transferred into a vertex list by appending a third column containing the z -coordinate such as zero or another z -coordinate.

- **VLaddz** for converting a point list (PL) into a vertex list (VL) by adding a 3rd column for the z -coordinate.
- **VLplot** for displaying in 3D a $n \times 3$ vertex list (VL).

```
VL=VLaddz(PL,1)
VLplot (VL,'bx-',2);
```

```
VL =
    0     0     1
    1     0     1
    1     1     1
    0     1     1
```

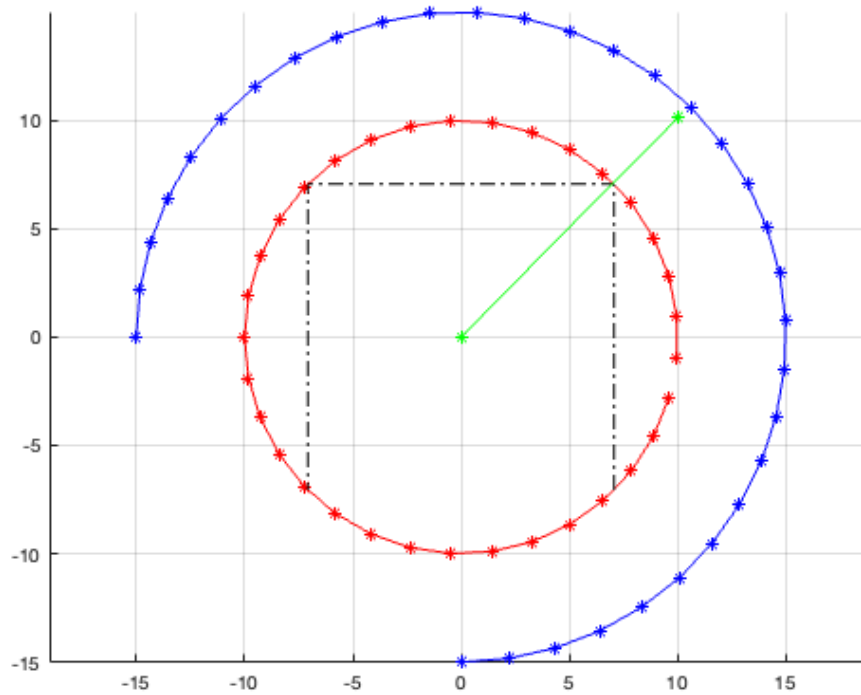


3. Predefined functions for the generation of often used planar polygons (PL)

For some often used contours, there are predefined functions that generate a nx2 coordinate point list (PL).

- **PLcircle** for a polygon with n points.
- **PLcircseg** for a circle segment with n points.
- **PLEvolvente** for an evolvente as contour.

```
close all;
PL=PLcircle (10,33); % Radius 10, 33 points
PLplot(PL); view (0,90); axis equal; grid on;
PL=PLcircle (10,4); % Radius 10, 4 points
PLplot(PL,'k-.'); view (0,90); axis equal; grid on;
PL=PLcircseg (15,33,-pi/2,+pi); % Radius 15, 33 points, 270 degree
PLplot(PL,'b-*'); view (0,90); axis equal; grid on;
PL=PLEvolvente (10,pi/180*270,33)'; % Radius 10, 33 points, 270 degree
PLplot(PL,'g-*'); view (0,90); axis equal; grid on;
```

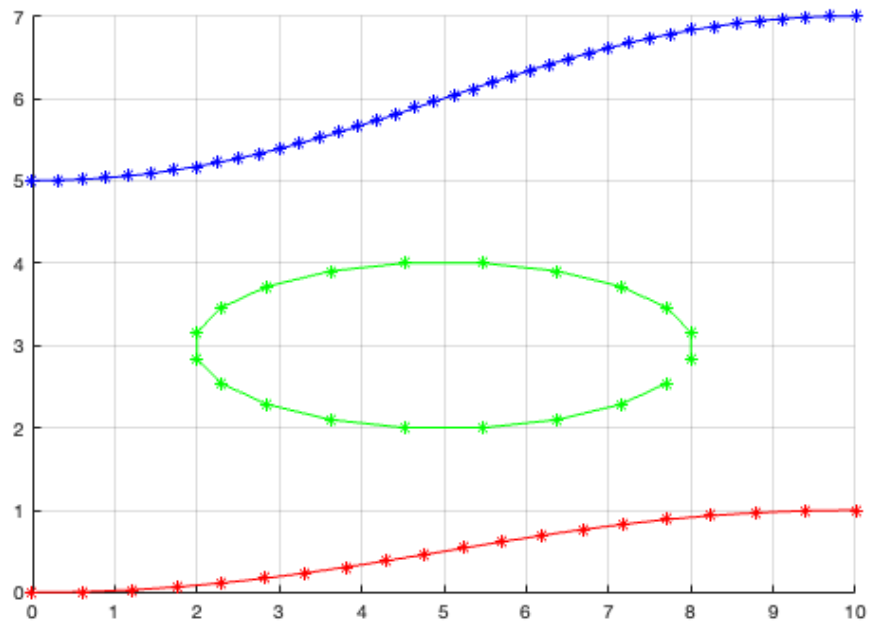


4. More predefined functions for planar polygons in 3D (VL)

Some functions for planar polygons create already 3D points (vertices) and the result of such a function is a vertex list (VL).

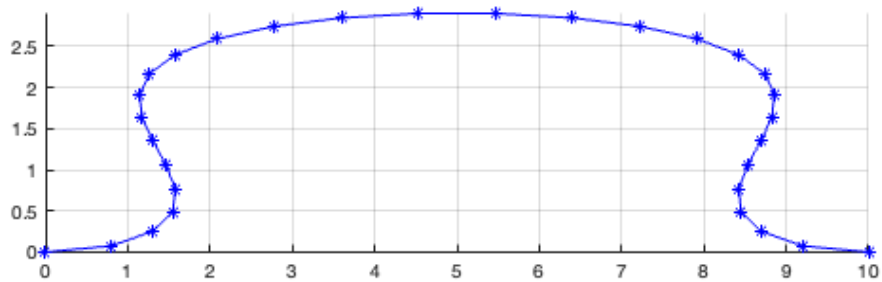
- **VLpolygon** to generate elliptic contours.
- **VLBezier4P** to generate a Bezier-curve using 4 points.
- **VLBezierC** to generate a Bezier-curve using as many points as possible.
- **VLremstraightCVL** to remove obsolete points on straight lines.

```
close all;
VL=VLpolygon(20,3,1,[5 3 0]);
VLplot (VL,'g*-'); show, axis equal, view (0,90); grid on; hold on;
VL=VLBezier4P([0 0 0],[4 0 0],[6 1 0],[10 1 0],20);
VLplot (VL,'r*-'); show, axis equal, view (0,90);
VL=VLBezierC([0 5; 4 5; 6 7; 10 7],40);
VLplot (VL,'b*-'); show, axis equal, view (0,90); grid on
```



- **VLBeziernoose** to generate a Bezier-curve spring-element.

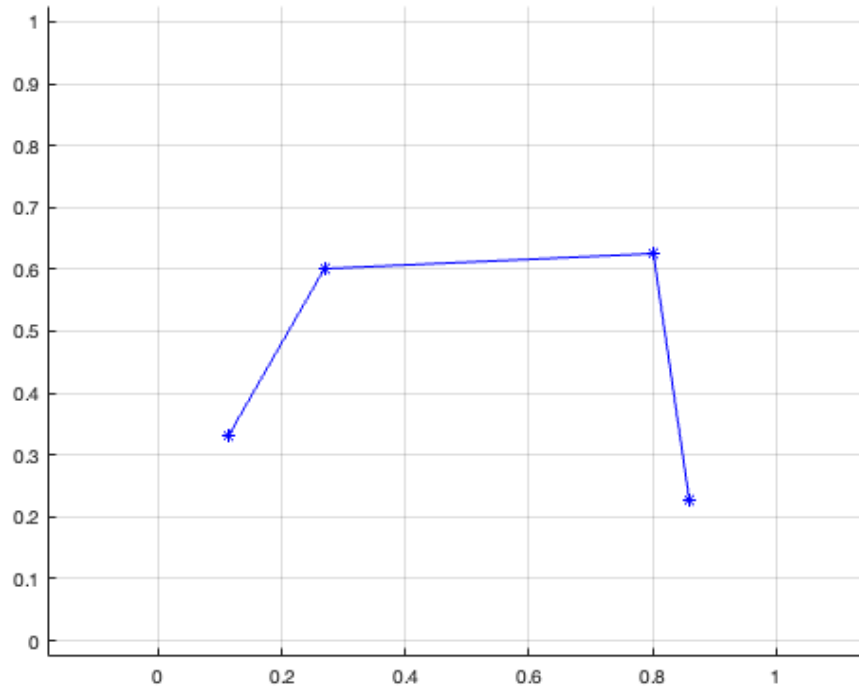
```
close all;
VL=VLBeziernoose(10,2,3,3,30);
VLplot (VL,'b*-'); show, axis equal, view (0,90); grid on
```



- **VLui** as an user interface to enter points by mouse clicks.

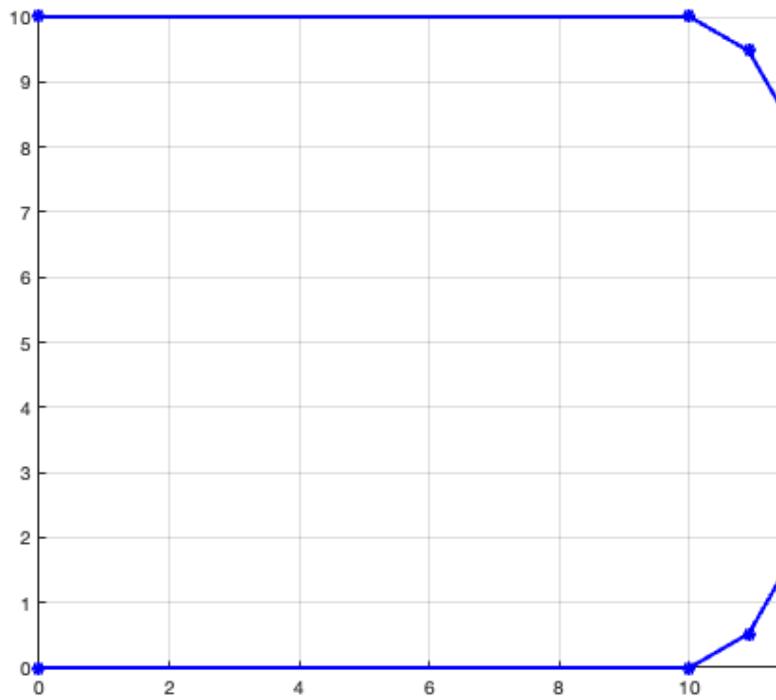
```
close all;
VL=VLui
VLplot (VL,'b*-' ); show, axis equal, view (0,90); grid on
```

```
VL =
    0.1141    0.3316    0
    0.2690    0.6010    0
    0.8012    0.6255    0
    0.8593    0.2276    0
```



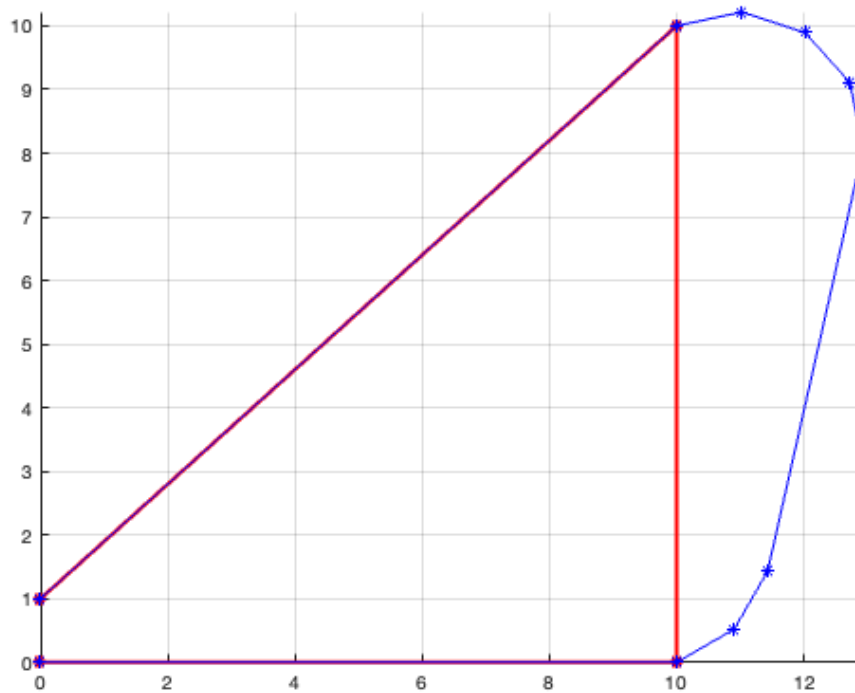
- **VLRadius4P** for inserting points to generate radial curves instead of corners.

```
close all
VL=VLRadius4P([0 0 0],[10 0 0], [10 10 0], [0 10 0], pi/6, 2);
VL=VLremstraightCVL (VL);
VLplot (VL,'b*-',2); show, axis equal, view (0,90); grid on
```



- **VLRadiusC** for inserting points to generate radial curves instead of corners.

```
close all
VLORG=[[0 0 0];[10 0 0];[10 10 0];[0 10 0]];
VLplot (VLORG, 'r*- ',2); show, axis equal, view (0,90); grid on; hold on
VL=VLRadiusC(VLORG, pi/6, 2);
VL=VLremstraightCVL (VL);
VLplot (VL, 'b*- ',1); show, axis equal, view (0,90); grid on
```

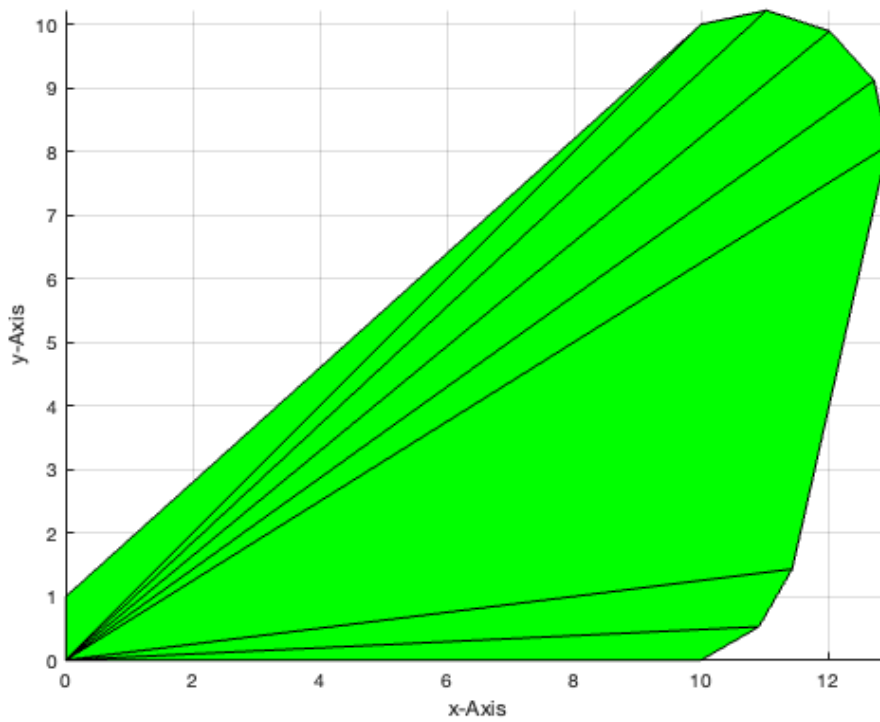
5. Calculation of the surface of a convex polygon

If we have a closed convex polygon, it is possible to generate a surface description by a facet list (FL) describing triangle facets. This is called tessellation of the closed polygon/surface. For closed convex polygons, the simplest form are facets from the 1st to the 2nd and 3rd points [1 2 3], then from the 1st to the 3rd and 4th [1 3 4], and so on. The facet list (FL) is therefore a $n \times 3$ index list to the point list or vertex list (VL). To use this concept we have some basic functions. For non convex functions we see later some more solutions.

- **FLoFVL** to generate the facet list (FL) for a **convex** polygon.
- **VLFLplot** to plot a surface given by a vertex list (VL) and a facet list (FL).

```
close all
FL=FLoFVL(VL)
% FL=FLoFCVL(VL)
VLFLplot (VL,FL,'g'); axis equal; view (0,90); grid on
% view (-30,30);
```

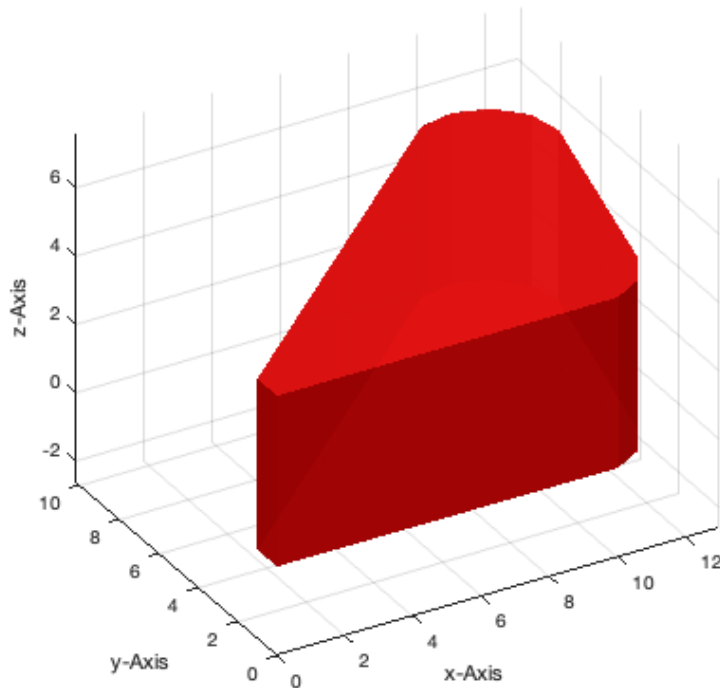
```
FL =
     1     2     3
     1     3     4
     1     4     5
     1     5     6
     1     6     7
     1     7     8
     1     8     9
     1     9    10
```



6. Calculation of all surfaces of convex polygon-based 2.5D-solid-volumes

- **VLFLofPLz** to extrude a convex polygon to a solid volume.
- **VLFLplotlight** to adjust the rendering parameter of the current graphic.

```
close all
[VL,FL]=VLFLofPLz (VL(:,1:2),5);
VLFLplot (VL,FL); axis equal; view (-30,30); grid on
VLFLplotlight(1,0.9); show;
```

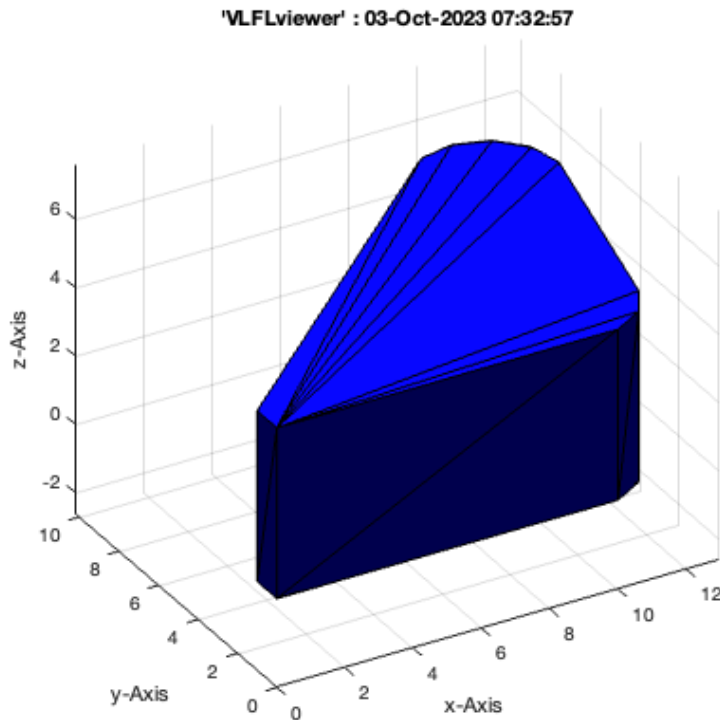


7. Graphical user interface for STL import, export, and viewing

Currently tested only for OSX (Apple Macintosh), there is also a graphical user interface available for displaying the surface objects, to import STL-Files and to export STL-Files. In this example, the tool is just introduced, to explain the capabilities to implement also graphical design tools for solid object modeling.

- **VLFLviewer** to show surface models, to import and to export STL-Files.

```
VLFLviewer (VL,FL,'b'); view (-30,30);
```



VLFLlicense

```
% * Tim Lueth, tested and compiled on OSX 10.7.5 with Matlab 2014b on 2014-11-18
% * Tim Lueth, executed and published on 64 Bit PC using Windows with Matlab 2014b on 2014-11-18
```

This VLFL-Lib, Rel. (2023-Oct-03), is for limited non commercial educational use only!

Licensee: Tim Lueth (Development Version)!

Please contact Tim Lueth, Professor at TU Munich, Germany!

WARNING: This VLFL-Lib (Rel.) license will exceed at 06-Jul-2078 07:32:58!

Executed 03-Oct-2023 07:33:00 by 'timlueth' on a MACI64 using Mac OSX 13.6 | R2023a Update 5 | SG-Lib 5.4

===== Used Matlab products: =====

```
database_toolbox
distrib_computing_toolbox
fixed_point_toolbox
image_toolbox
map_toolbox
matlab
optimization_toolbox
pde_toolbox
phased_array_system_toolbox
signal_blocks
signal_toolbox
simmechanics
simscape
simulink
statistics_toolbox
=====
```