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#### SMiLe: Automated End-to-end Sensing and Machine Learning Co-Design

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Towards Machine Learning at the Edge





Towards Machine Learning at the Edge





Challenges





Challenges





# Migration from Cloud Analytics to Edge Analytics

Our 3-fold Approach

#### Optimization

• Make clever decisions to co-design Sensing and Machine Learning

#### Hardware-in-the-loop

• Measure performance directly on the edge system

#### Automation

• Mitigate time consuming manual tuning

In our paper, we deliver an automated framework focussing on optimizing the Sensing and Machine Learning Co-Design using feedback from Hardware-in-the-loop

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# *SMiLe*: Automated End-to-end Sensing and Machine Learning Co-Design



### *SMiLe* framework

Automated end-to-end edge analytics



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ABB



## SMiLe – ABB Solution to Edge Analytics

Automated end-to-end edge analytics



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# *SMiLe* : Automated End-to-end Sensing and Machine Learning Co-Design



#### **Sensing Parameters**

Sampling Frequency and Sensing Window



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### Need for Sensing and ML Co-Design

Impact of Sampling Frequency











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October 4 | Slide 10 SMiLe : Automated End-to-end Sensing and Machine Learning Co-Design, T.Goyal, P.Huang, F.Sutton, B.Maag and P.Sommer, EWSN, October 3-5, 2022



### Need for Sensing and ML Co-Design

Impact of Sensing Window Size





### Sensing and ML Co-Optimization

Co-Optimization of sensing and ML using SMiLe





## Parallel Co-Optimization of *SMiLe*

Co-Optimization of sensing and ML using *SMiLe* 





## Sensing and ML Co-Optimization

Multi-objective optimization



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# *SMiLe* : Automated End-to-end Sensing and Machine Learning Co-Design



### Motor Testbed @ ABB Swiss Research Center

Infrastructure

![](_page_17_Figure_2.jpeg)

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![](_page_17_Picture_5.jpeg)

**Problem Formulation** 

#### **Bearing Fault Creation**

![](_page_18_Picture_3.jpeg)

and 1g metallic dust

#### Problem

- Type: A 3-class classification problem (0g, 0.25g and 1g of metallic dust)
- Input Data: Acceleration
- **Objective:** Perform Multi-objective optimization based on Accuracy, # Parameters, Energy and Latency

![](_page_18_Picture_9.jpeg)

**Design Space** 

![](_page_19_Figure_2.jpeg)

#### Total possible Configurations: 13,440,000,000

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![](_page_19_Picture_5.jpeg)

Sampling frequency – how often should we read the sensor?

![](_page_20_Figure_2.jpeg)

 Sensing Energy 
 <sup>1</sup>
 Sampling Frequency

- Inference Energy and # Parameters are highly correlated
- Inference Energy has a convex trend with Sampling Frequency; thus it has a minima
- Need to explore design space using *SMiLe* for finding the minima of Inference Energy

#### Reduce energy requirement by finding optimal sampling frequency using *SMiLe*

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![](_page_20_Picture_10.jpeg)

Sensing Window (# Samples) – what is a good amount of data for ML prediction

![](_page_21_Figure_2.jpeg)

- Sensing Energy ∝ Sensing Window Size
- Inference energy < Sensing Window Size (with few outliers)
- # Parameters follow no clear trend with Sensing Window Size
- Need to explore design space using *SMiLe* for finding the minimum *#* Parameters

#### Reduce energy requirement by decreasing Sensing Window size

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#### SMiLe exploration

8-hour experiment for Motor Health Prediction

**Exploration of Hyper-Parameters** 60 100 ر ا **S**14000 **1**2000 45 75 0.98 8000 8000 Count Count 30 50 **Ā** 0.96 **Validation** 0.94 Validation ã 6000 #Models 15 25 4000 2000 0 0 25 50 100 150 200 300 400 700 12.5 26 52 104 208 416 833 1660 40 50 60 70 80 90 100 110 #Models Trained 40 50 60 70 80 90 100 110 **#Models Trained** 10 20 30 20 30 10 Sampling Frequency (Hz) **Sensing Window Size** 20 **Sensing Energy (mJ)** 20 100000 **Metric** 80000 80000 8 15 15 Count Count 6 60000 10 10 Global 40000 5 5 20000 2 0 20 30 40 50 60 70 80 90 100 110 10 10 20 30 40 50 60 70 80 90 100 110 4 7 10 13 16 19 19 25 30 35 40 46 5 1 **#Models Trained #Models Trained Kernel Size** # of Channels SMiLe design space exploration

#### **Evolution of various metrics**

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## *SMiLe* for Edge Analytics

**Results for Motor Health Prediction** 

![](_page_23_Figure_2.jpeg)

![](_page_23_Picture_5.jpeg)

![](_page_24_Figure_0.jpeg)

#### Our Contributions ...

- ... *SMiLe* for automated optimization of sensing and machine learning Co-Design
- ... optimization based on real-time feedback from Hardware-in-the-loop
- ... validation of *SMiLe* on real-world use case Motor Health Prediction

#### Our Results show that ...

- ... sensing Hyper-Parameters are important to be optimized alongside ML
- ... SMiLe significantly reduces exploration time and improves exploration results
- ... Hardware-in-the-loop enables direct optimization of energy and latency

![](_page_24_Picture_10.jpeg)

![](_page_25_Picture_0.jpeg)

#### Motivation

#### Impact of SMiLe on Real world use case - Motor Health Prediction

![](_page_26_Figure_2.jpeg)

\*Real-time motor fault detection by 1-d convolutional neural networks. IEEE Transactions on Industrial Electronics, 63(11), 2016; A deep autoencoder-based CNN framework for bearing fault classification in induction motors. Sensors, 21(24), 2021; Deep Learning & its applications to machine health monitoring. Mechanical Systems & Signal Processing, 115, 2019 October 4 Slide 3 Energy requirements & Latency are minimum when 2022 Sensing & ML, parameters are co-optimized using *SMiL e* 

![](_page_27_Picture_0.jpeg)

#### **ML Data Processing Pipeline**

Frontend – Analysis & Model Development

![](_page_27_Figure_3.jpeg)

![](_page_27_Picture_5.jpeg)

#### TVM/OctoML

![](_page_28_Figure_1.jpeg)

![](_page_28_Figure_2.jpeg)

Figure 5: Overview of the SMiLe machine learning backend

![](_page_28_Figure_4.jpeg)