

Model Reduction to Invariant Manifolds

Overview on the Direct Parameterisation of Invariant Manifolds

Methodology

The full-order model is an N-dimensional autonomous DAE: $\mathbf{B}\dot{m{y}}=\mathbf{A}(m{y})$, with equilibrium at the origin. To construct a reduced-order model of dimension $n \ll N$, we seek an ODE $\dot{m{z}}\!=\!{f f}({m{z}})$ and mapping $oldsymbol{y}\!=\!\mathbf{W}(oldsymbol{z})$ that preserve the system's essential dynamics near the equilibrium. Directly solving the resulting functional equation, $\mathbf{B} \,
abla \mathbf{W} \cdot \mathbf{f} = \mathbf{A} \circ \mathbf{W}$, is still intractable. Hence, we assume power series expansions for A, W and f. So, the coefficients can be determined recursively for each monomial $m{z}^{\mathbf{p}} = z_1^{p_1} z_2^{p_2} \cdots z_n^{p_n}$

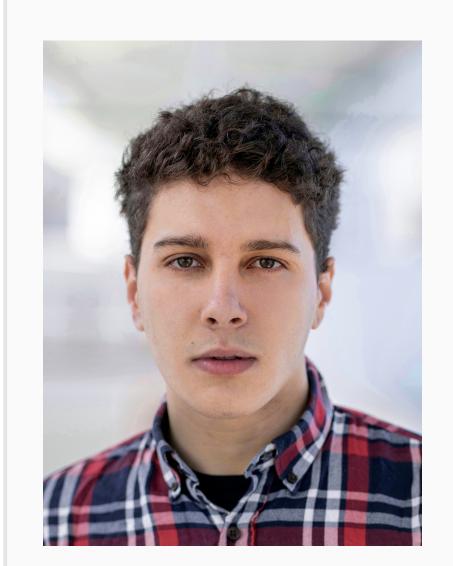
Adaptable to:

Mechanical systems

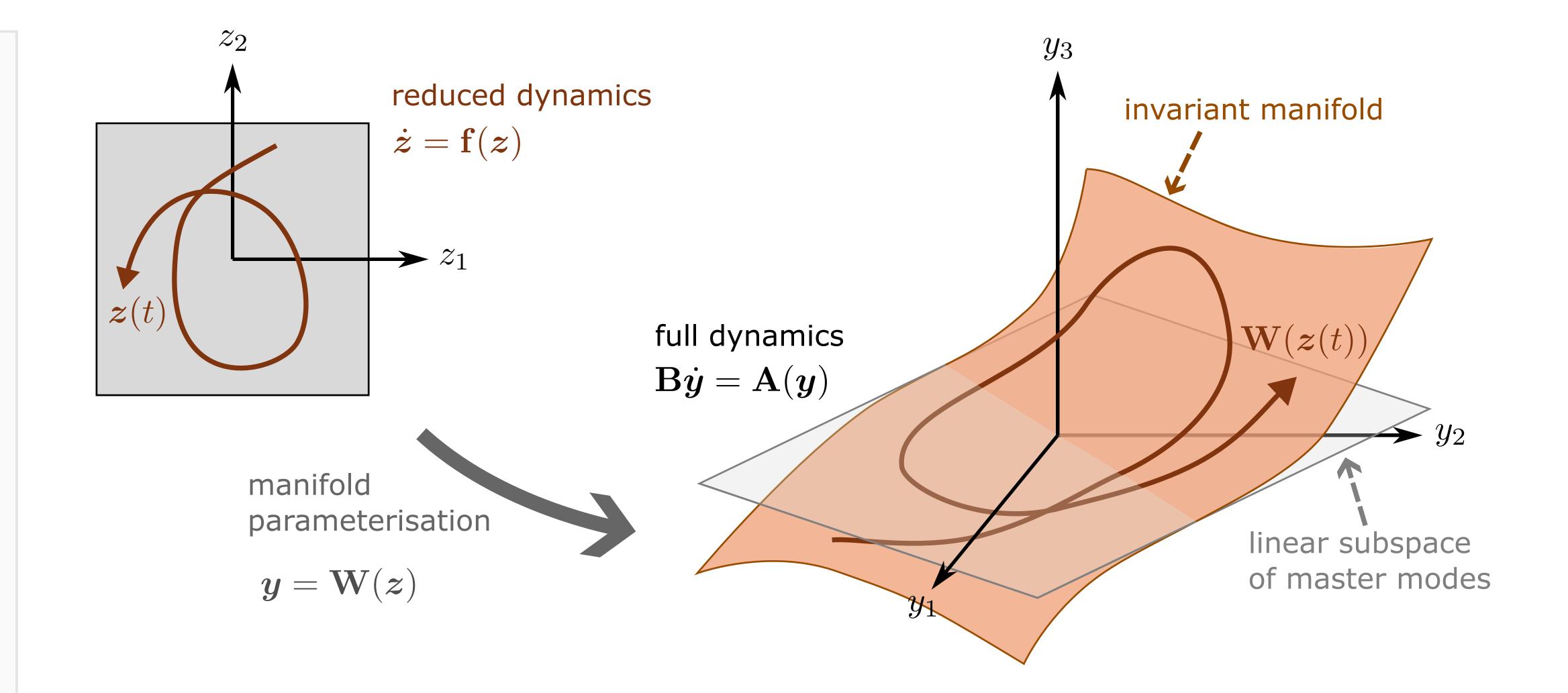
via the corresponding

homological equation.

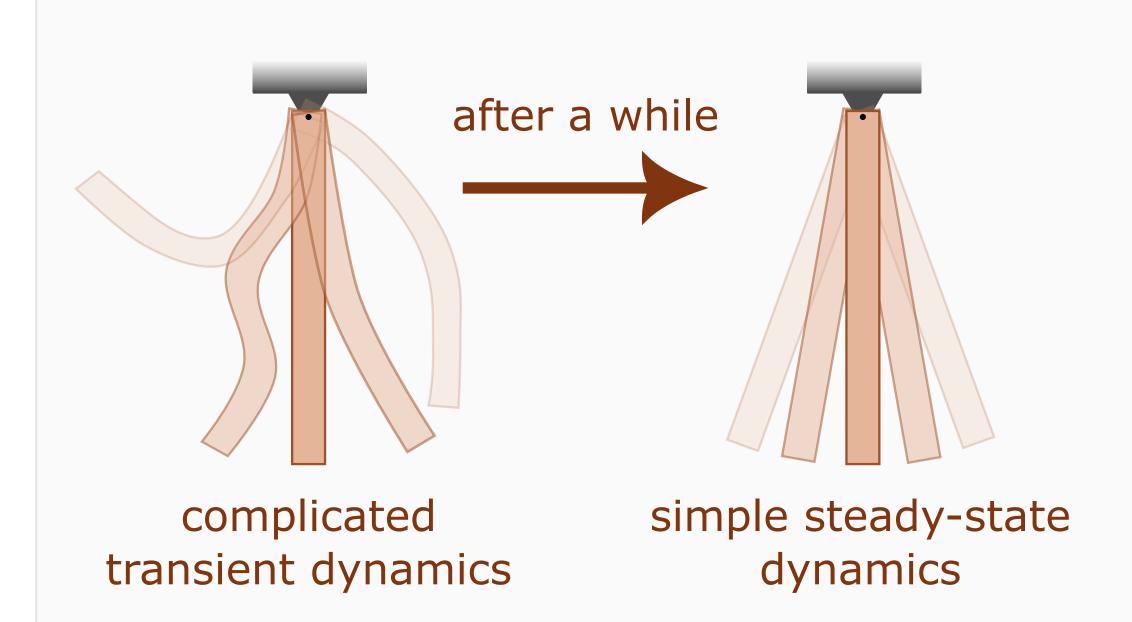
- Smooth forcing
- Algebraic constraints
- Varying parameters
- Retain variables of the full model in the ROM



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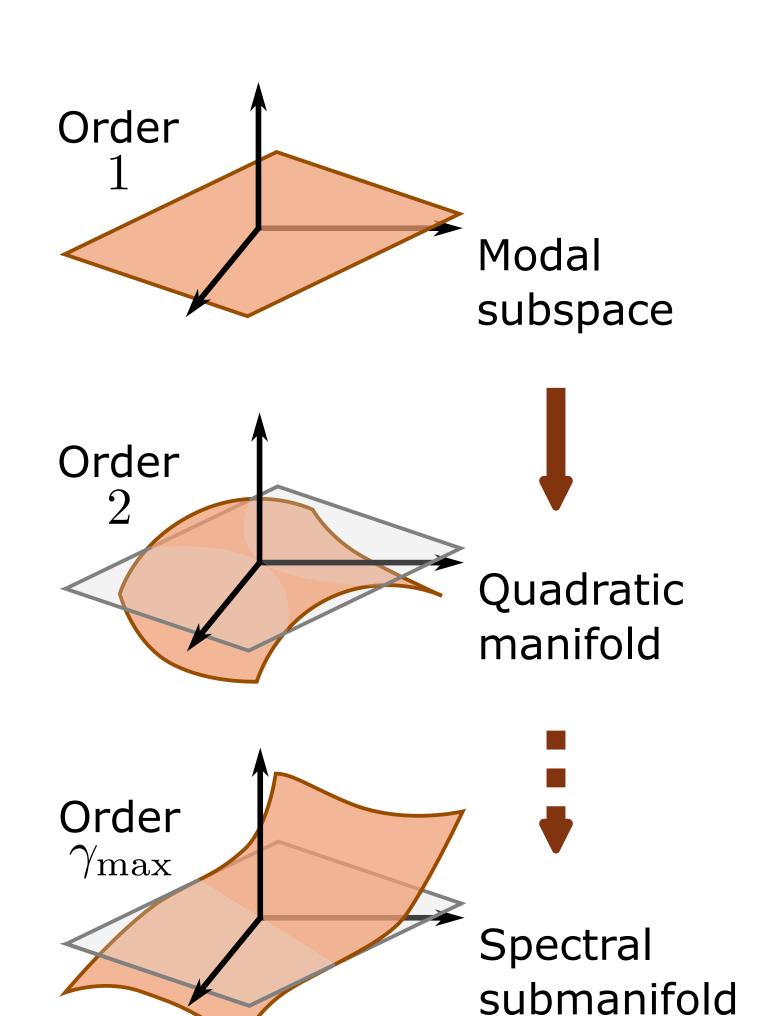
Slow and Attracting Invariant Manifold



state-space representation

The system quickly tends to states inside the invariant manifold that has slow dynamics.

Inserting the ROM in the full dynamics yields the invariance equation: $\mathbf{B} \, \nabla \mathbf{W} \cdot \mathbf{f} = \mathbf{A} \circ \mathbf{W}$.



$$\mathbf{A}(oldsymbol{y}) = \sum_{N} \mathbf{A}_{oldsymbol{lpha}} oldsymbol{y}_{N}^{lpha}, \quad \mathbf{W}(oldsymbol{z}) = \sum_{N} \mathbf{W}_{oldsymbol{\sigma}} oldsymbol{z}^{oldsymbol{\sigma}}, \quad \mathbf{f}(oldsymbol{z}) = \sum_{N} \mathbf{f}_{oldsymbol{
u}} oldsymbol{z}^{oldsymbol{
u}}$$

Find master eigenmodes, i.e. order 1 monomials. $\mathbf{BW_1f_1} = \mathbf{A_1W_1}$ $\sim [\lambda_k \mathbf{B} - \mathbf{A_1}] \mathbf{W_{e_k}} = \mathbf{0}$ $\gamma = 2$ Solve all monomials $\mathbf{BW_1f_p} + [(\boldsymbol{\lambda} \cdot \boldsymbol{p})\mathbf{B} - \mathbf{A_1}] \mathbf{W_p}$ $\mathbf{p} \text{ of order } |\mathbf{p}| = \gamma \,.$ $= \mathrm{RHS}(\mathbf{A}_{\leq |\boldsymbol{p}|}, \mathbf{W}_{<|\boldsymbol{p}|}, \mathbf{f}_{<|\boldsymbol{p}|})$

Reference

Vizzaccaro, A., Gobat, G., Frangi, A. et al. Direct parametrisation of invariant manifolds for non-autonomous forced systems including superharmonic resonances. Nonlinear Dyn 112, 6255–6290 (2024).