

Tutorial 52: CPL Buffers and cw/ccw Orientation

2020-01-04: Tim C. Lueth, Professor at Technische Universität München, Germany (URL: <http://www.SG-Lib.org>) - Last Change: 2020-01-04

Contents

- [Complete List of all Tutorials with Publishable MATLAB Files of this Solid-Geometries Toolbox](#)
- [Motivation for this tutorial: \(Originally SolidGeometry 4.8 required\)](#)
- [Final Remarks](#)

Complete List of all Tutorials with Publishable MATLAB Files of this Solid-Geometries Toolbox

The following topics are covered and explained in the specific tutorials:

- Tutorial 01: First Steps Using the VLFL-Toolbox for Solid Object Design
- Tutorial 02: Using the VLFL-Toolbox for STL-File Export and Import
- Tutorial 03: Closed 2D Contours and Boolean Operations in 2D
- Tutorial 04: 2½D Design Using Boolean Operators on Closed Polygon Lists (CPL)
- Tutorial 05: Creation, Relative Positioning and Merging of Solid Geometries (SG)
- Tutorial 06: Relative Positioning and Alignment of Solid Geometries (SG)
- Tutorial 07: Rotation of Closed Polygon Lists for Solid Geometry Design
- Tutorial 08: Slicing, Closing, Cutting and Separation of Solid Geometries
- Tutorial 09: Boolean Operations with Solid Geometries
- Tutorial 10: Packaging of Sets of Solid Geometries (SG)
- Tutorial 11: Attaching Coordinates Frames to Create Kinematik Models
- Tutorial 12: Define Robot Kinematics and Detect Collisions
- Tutorial 13: Mounting Faces and Conversion of Blocks into Lightweight-structures
- Tutorial 14: Manipulation Functions for Closed Polygons and Laser Cutting (SVG)
- Tutorial 15: Create a Solid by 2 Closed Polygons
- Tutorial 16: Create Tube-Style Solids by Succeeding Polygons
- Tutorial 17: Filling and Bending of Polygons and Solids
- Tutorial 18: Analyzing and modifying STL files from CSG modeler (Catia)
- Tutorial 19: Creating drawing templates and dimensioning from polygon lines
- Tutorial 20: Programmatically Interface to SimMechanics Multi-Body Toolbox
- Tutorial 21: Programmatically Convert Joints into Drives (SimMechanics)
- Tutorial 22: Adding Simulink Signals to Record Frame Movements
- Tutorial 23: Automatic Creation of a Missing Link and 3D Print of a Complete Model
- Tutorial 24: Automatic Creation of a Joint Limitations
- Tutorial 25: Automatic Creation of Video Titels, Endtitels and Textpages
- Tutorial 26: Create Mechanisms using Universal Planar Links
- Tutorial 27: Fourbar-Linkage: 2 Pose Syntheses and Linkage Export for 3D Printing
- Tutorial 28: Fourbar-Linkage: 3 Pose Syntheses and Linkage Export for 3D Printing
- Tutorial 29: Create a multi body simulation using several mass points
- Tutorial 30: Creating graphical drawings using point, lines, surfaces, frames etc.
- Tutorial 31: Importing 3D Medical DICOM Image Data and converting into 3D Solids
- Tutorial 32: Exchanging Data with a FileMaker Database
- Tutorial 33: Using a Round-Robin realtime multi-tasking system
- Tutorial 34: 2D Projection Images and Camera Coordinate System Reconstruction
- Tutorial 35: Creation of Kinematic Chains and Robot Structures
- Tutorial 36: Creating a Patient-Individual Arm-Skin Protector-Shell
- Tutorial 37: Dimensioning of STL Files and Surface Data
- Tutorial 38: Some more solid geometry modelling function
- Tutorial 39: HEBO Modules robot design
- Tutorial 40: JACO Robot Simulation and Control
- Tutorial 41: Inserting Blades, Cuts and Joints into Solid Geometries
- Tutorial 42: Performing FEM Stress and Displacement Analysis and Structural Optimization of Solids
- Tutorial 43: Performing FEM Structural Optimization (CAO) and Topological Optimization (SKO) of Solids
- Tutorial 44: Creation of solids and kinematics from 3D curves and transformation matrices

- Tutorial 45: Creation of Solids using the SG-Coder - SGofCPLcommand
- Tutorial 46: Creating Fischertechnik compatible gear boxes using SGofCPLcommand
- Tutorial 47: Creating four-joints by 3 pose synthesis
- Tutorial 52: CPL Buffers and cw/ccw Orientation

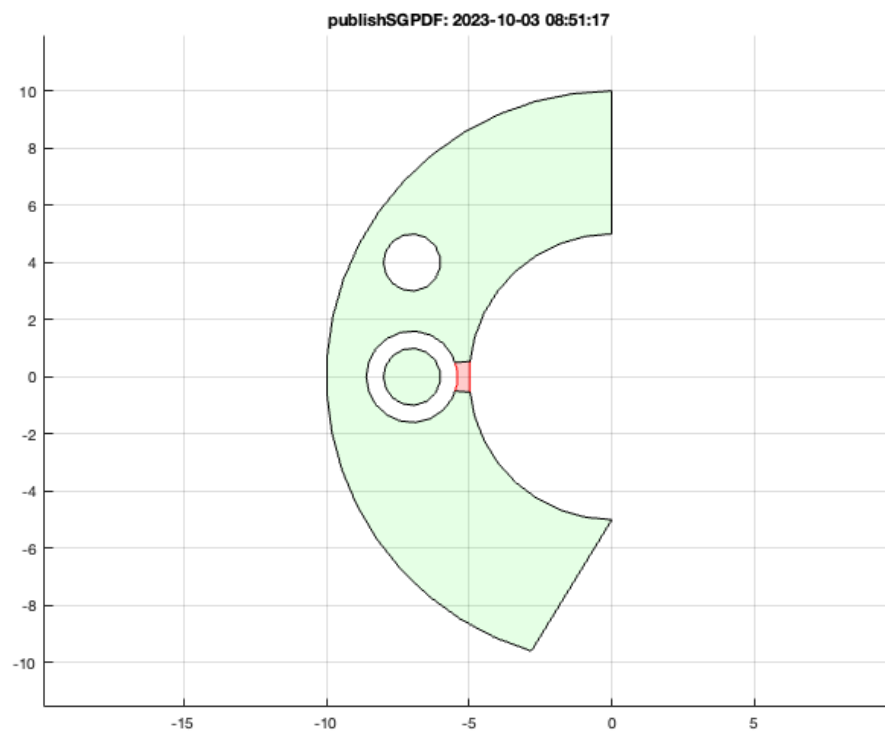
Motivation for this tutorial: (Originally SolidGeometry 4.8 required)

```
%In connection with the development of skeleton functions, there is always a need for CPL buffer functions.
%
% function VLFL_EXP52
```

We are looking for the regions of a CPL that have a wall distance smaller than 0.7 mm. These regions may not be 3D printable

```
CPLfindsmallldist(CPLsample(29),.7)
```

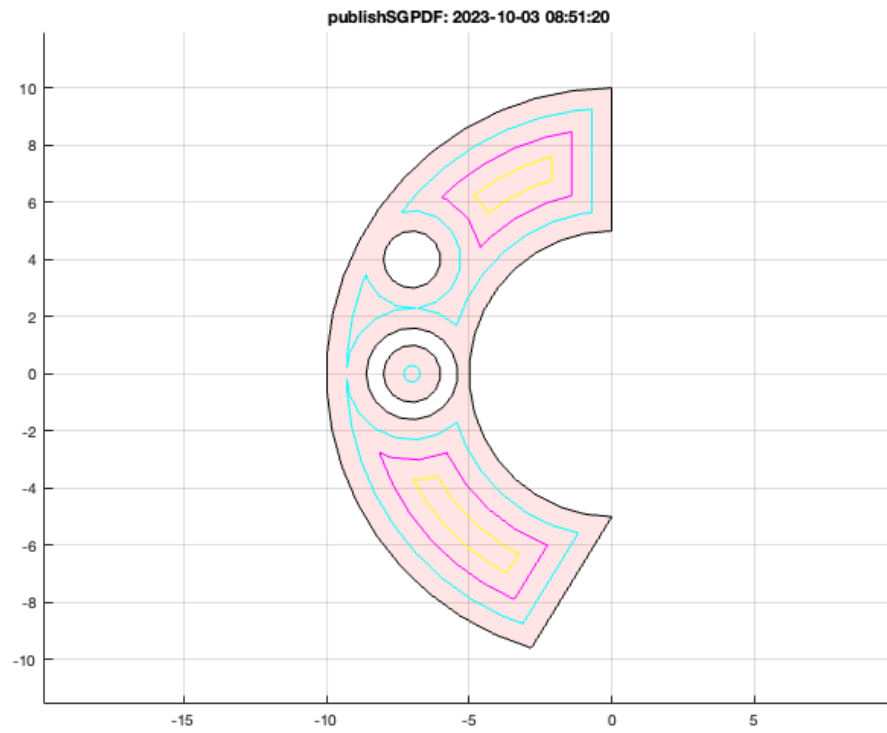
```
ans =
-4.9787 -0.4613
-4.9645 -0.5374
-5.5024 -0.4981
-5.4218 -0.2634
-5.4218 0.2634
-5.5024 0.4981
-4.9645 0.5374
-4.9787 0.4613
```



Sometimes you search for all lines in a defined distance to a Contour edge in a fixed distance grid

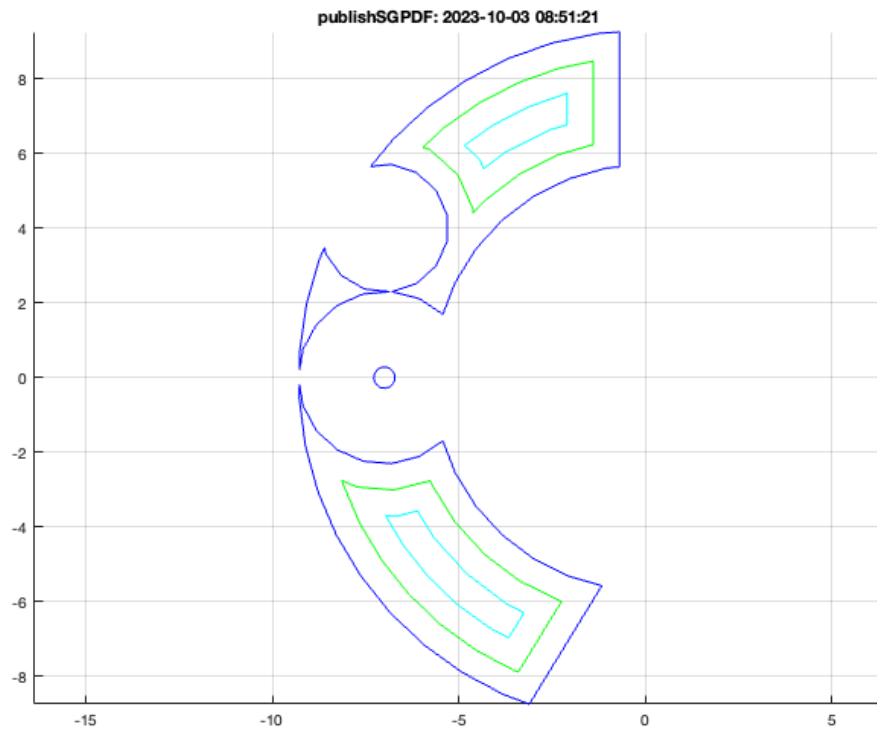
```
CPLbufferlines(CPLsample(29),.7)
```

```
ans =
4x2 cell array
{[ 0]} {92x2 double}
{[0.7000]} {82x2 double}
{[1.4000]} {34x2 double}
{[2.1000]} {23x2 double}
```



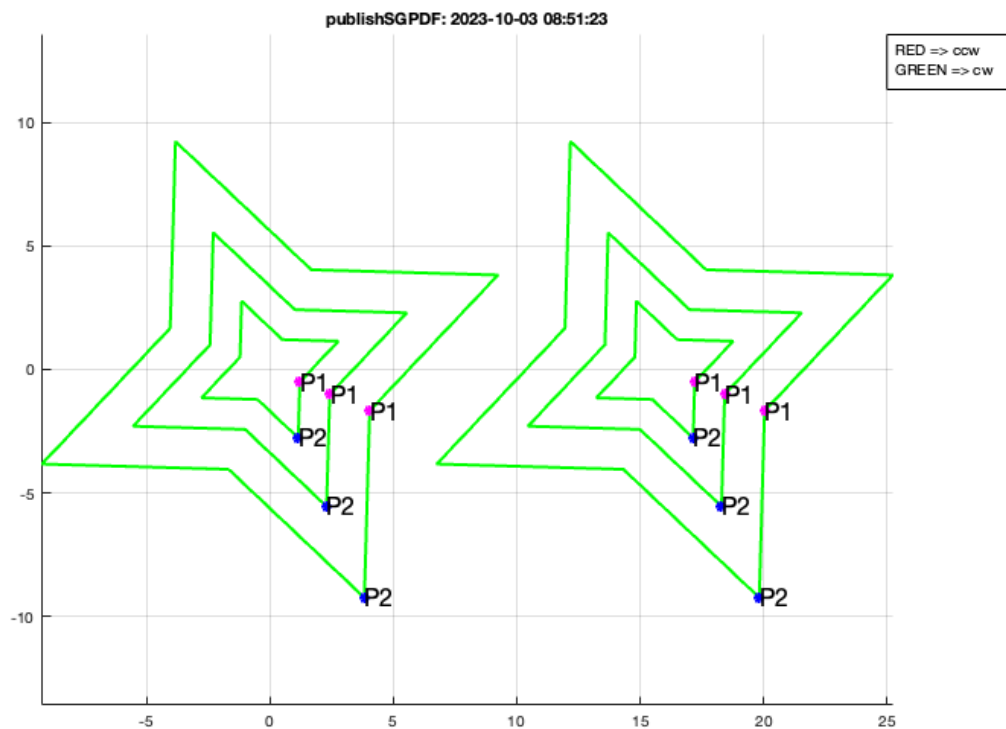
Sometimes you just want to get them plotted

```
SGfigure;CPLplotbufferlines(CPLsample(29),.7);
```



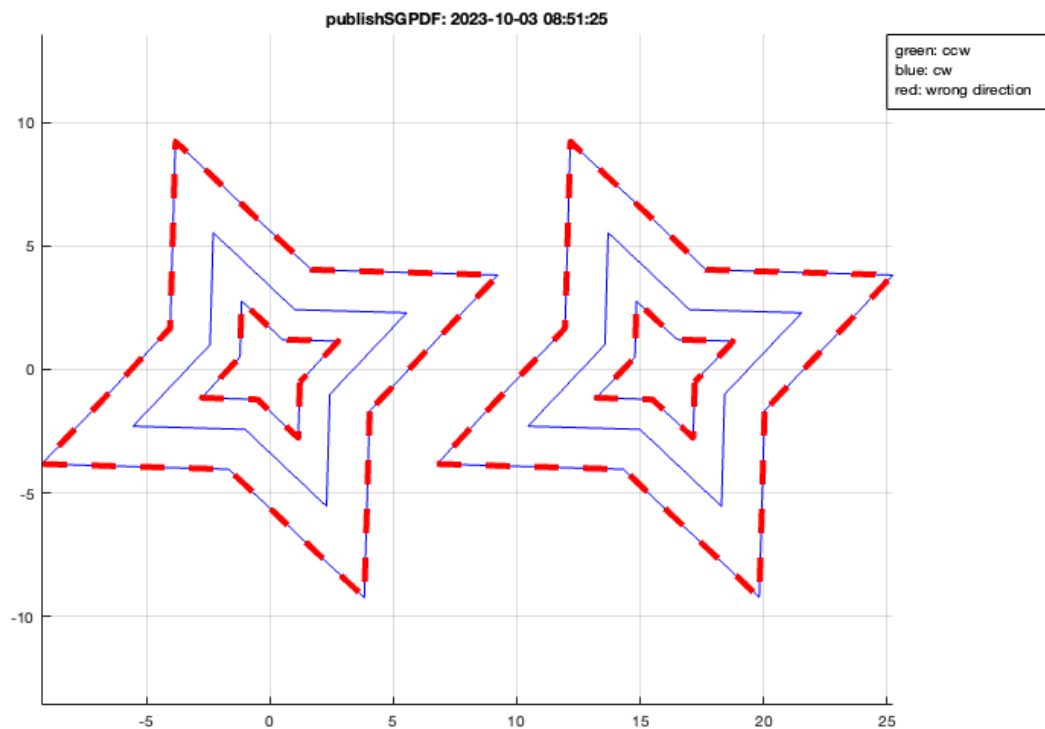
There is a function that intentionally changes the direction of rotation of all Contours is set to Clockwise.

```
CPLsetallcw(CPLsample(14));
```



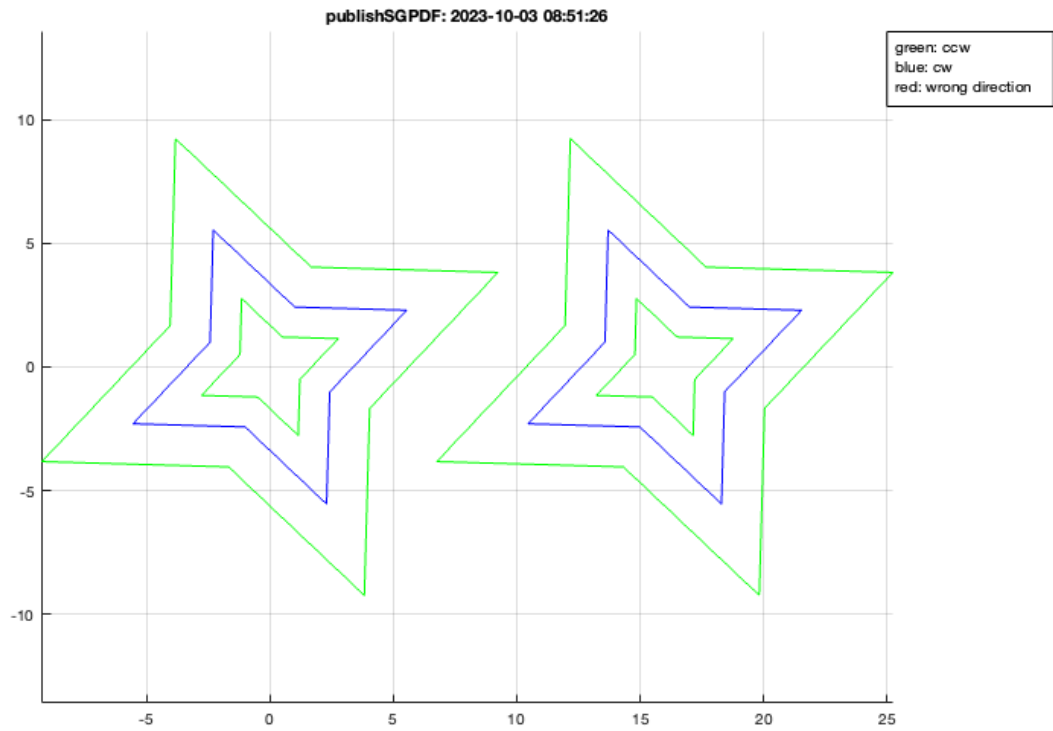
There is a function that indicates whether a CPL in the direction of rotation is correct as in the SG-lib. ccw is outside; cw is inside

```
CPLiscwinout(CPLsetallcw(CPLsample(14)));
```



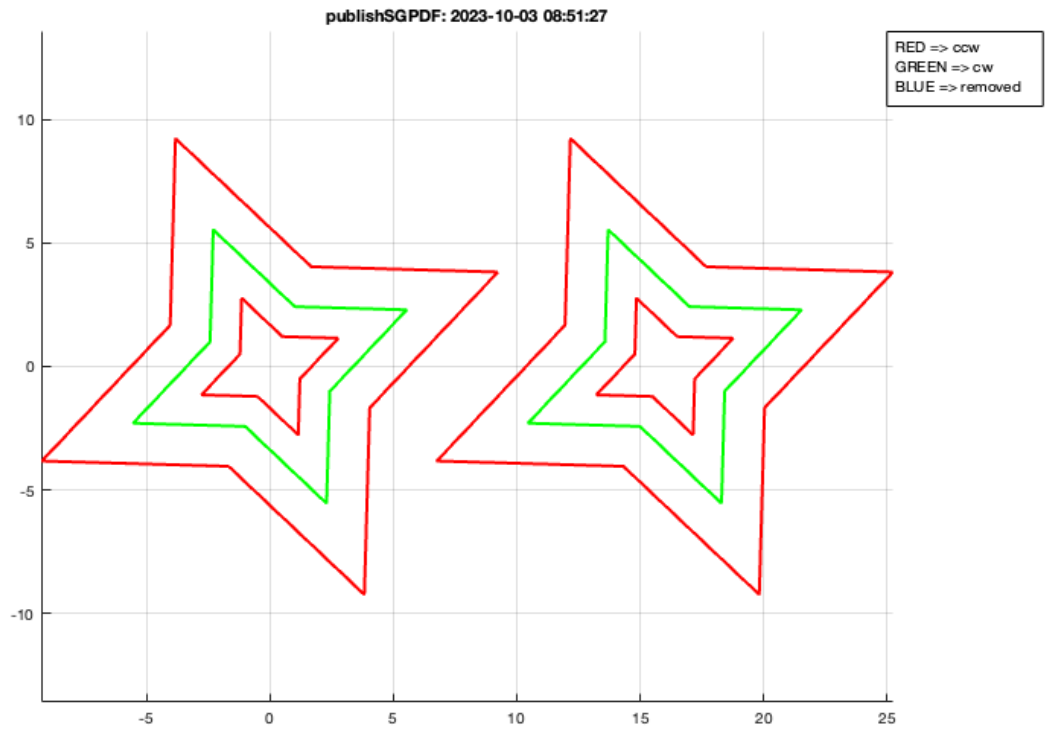
There is a function for correcting the direction of rotation of contours depending on the nesting depth within the contours

```
CPLisccwcorrected(CPLsetallcw(CPLsample(14)));
```



In the meantime there is a faster function based on the Polyshapes

```
CPLisccwcorrectedCPS(CPLsetallcw(CPLsample(14)));
```



Final Remarks

```
close all
VLFLlicense
```

This VLFL-Lib, Rel. (2023-Oct-03), is for limited non commercial educational use only!

Licensee: Tim Lueth (Development Version)!

Please contact Tim Lueth, Professor at TU Munich, Germany!

WARNING: This VLFL-Lib (Rel.) license will exceed at 06-Jul-2078 08:51:28!

Executed 03-Oct-2023 08:51:30 by 'timlueth' on a MACI64 using Mac OSX 13.6 | R2023a Update 5 | SG-Lib 5.4

===== Used Matlab products: =====

```
database_toolbox
distrib_computing_toolbox
fixed_point_toolbox
image_toolbox
map_toolbox
matlab
optimization_toolbox
pde_toolbox
simmechanics
simscape
simulink
=====
```

Published with MATLAB® R2023a